

Object Tracking Information System Based on Statistical Measurements

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ABSTRACT

Real images may consist of many objects. These objects may be situated in different directions. Object tracking is an important process for identification of objects via the captured image. The main objective of this work is to construct an efficient information algorithm that detects the direction of objects. This algorithm is designed and implemented based on statistical measurements, histogram, entropy, moment and gradient. The obtained results indicate that this algorithm leads merging many techniques to generate an efficient and effective approach.

Keywords: Object Identification, Object Tracking, Object Recognition, Statistical Measurements, Entropy Measurements.

1. INTRODUCTION

The image can be represented as a two dimensional function of two real variables $f(x,y)$, where x,y represent the spatial coordinates, and the function amplitude f given at any pair of coordinates is called the intensity or grey level of the image at that point. When x , y and the amplitude f are all finite and discrete quantities, we have a digital image. A digital image consists of a rectangular map of the image's pixels. The number of bits used for each pixel is called the bit depth. For monochrome image, e.g., the bit depth is 1 bit (to represent black or white), and the bit depth of the grey image is 8 bits to display 256 different shades of grey. Using entropy based methods for image processing has been a well-established approach in computer science for quite some time [1]. German et al. (2005) used entropy analysis for high dynamic range image processing. Yan et al. (2003) used entropy calculations for grey-scale image clarification required in the field of medical imagery. Basic tools for entropy based image processing are implemented in a variety of software applications. For example, Gonzalez et al. (2009) describe these tools' implementation in MATLAB [2,3] and Al-Ani et al. (2013) described a method of 3D visualization based on surface estimation techniques [4].

2. STATISTICAL MEASUREMENTS

The statistical measurements are very important especially when you have big amount of data, that is really exist in image processing. One of the important measurement is the mean (average) value in which we can see the concentration average value of pixels in which it can be measured as below [5,6]:

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

Where x_i represents the input and i represents the indexing values and n represents the number of inputs. Another statistical measurement is the standard deviation value that is calculated as:

$$s = \sqrt{\frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})^2}$$

Another statistical measurement is the entropy value that is calculated expressed in terms of a discrete set of probabilities p_i :

$$\text{Entropy} = - \sum_{i=0}^n p(x_i) \log p(x_i)$$

3. LITERATURE REVIEWS

Many works are published in this field:

Mohamed A. El-Sayed et al. (2011), presented an approach utilizing an improvement of Baljit and Amar method which uses Shannon entropy other than the evaluation of derivatives of the image in detecting edges in gray level images has been proposed. The proposed method can reduce the CPU time required for the edge detection process and the quality of the edge detector of the output images is robust [7].

M. Portes de Albuquerque et al. (2004) designed an approach uses the Shannon entropy originated from the information theory considering the gray level image histogram as a probability distribution. In this paper, Tsallis entropy is applied as general entropy formalism for information theory. For the first time image thresholding by non-extensive entropy is proposed regarding the presence of non-additive information content in some image classes [8].

Ewa Skubalska-Rafaajlowicz (2008), aimed to propose two methods of detecting defects in industrial products by an analysis of gray level images with low contrast between the defects and their background. An additional difficulty is the high non-uniformity of the background in different parts of the same image. Non-parametric estimator of local entropy is also proposed, together with its realization as a bank of RBF neural networks. The performance of both methods is done with an industrial image [9].

E.Pasha et al. (2006), implemented a new cost function is introduced by using the fuzzy entropy to choose a threshold value in image de-noising problem. Fuzzy entropy as a measure of image blurring has an important role in image processing. The best image is an image that has the lower distance of ideal image and in addition to the lower entropy. Thus fuzzy entropy cost function is a useful cost function in image processing. The results are explained with pilot this cost function on the some images [10].

Georgi Petrov et al. (2008), explained two functional models for entropy based image segmentation: using global 2D and 3D image histograms of grayscale images. We compare results obtained by both methods for different type of images such as: biomedical and micro objects, digital video records and natural photographs. Short introduction of multistage gradient 3D entropy segmentation for texture analysis is also introduced [11].

R.Sukanesh et al. (2007), designed a novel approach of information theory based Minimum Relative Entropy (MRE) and Entropy methods for image compression are discussed. A two stage compression process is performed through homogenous MRE method, and heterogeneous MRE. The compressed images are reconstructed through Region growing techniques. The performance of image compression and restoration is analyzed by the estimation of parametric values such as Mean Square Error (MSE) and Peak Signal to Noise Ratio (PSNR) [12].

Kitara Kadhim Al-Shayeh and and Muzhir Shaban Al-Ani (2009), purposed 3D object visualization via two dimensional (2D) images that included many object. The main objective of this work is to find the contour of the given object in each slice and then merging these contours to reconstruct the 3D objects. The proposed method is easy to use as well as it can be implemented on various type of images. The obtained results indicate a good resolution of the reconstruction process [13].

Zujun Hou et al. (2010), investigated the connection between histogram and image visibility, where the concept of entropy is employed to depict the information content of the histogram. It turns out that image visibility is more dependent on the observed intensity levels with higher frequencies and the distribution of their locations in the range of intensity levels. With this in mind, the concept of visible entropy is proposed. The usefulness of the proposed visibility measure has been evaluated using a number of realistic images [14].

M.C. Padma et al. (2010), presented a novel texture-based approach is presented to identify the script type of the documents printed in three prioritized scripts - Kannada, Hindi and English, prevailed in Karnataka, an Indian state. The document images are decomposed through the Wavelet Packet Decomposition using the Haar basis function up to level two. The texture features are extracted from the sub bands of the wavelet packet decomposition [15].

Muzhir Shaban Al-Ani, Kitara Kadhim Al-Shayeh (2010), studied the effects of image compression on face recognition algorithms, in which implemented some compression algorithms then the results were evaluated via the extracted features of face images.

4. THE PROPOSED APPROACH

Depending on the fact that said Entropy refers to measure of disorder of the system, so the proposed approach are constructed via the following steps as shown in figure1. Image acquisition step in which the objects are prepared with different directions to be ready for image capturing. Four different directions are forms to be the input images for the next step of the system. Image preprocessing, in which the input images were passed to gray scale processing, resizing, filtering, etc. to be fitted with the system. Histogram calculation, in which calculates number of pixels in each gray scale that represents an indication of pixels distribution. Entropy distribution step in which indicates the average information in

the entire image. Moment calculation step in which represents the central moments of all orders that is defined as the perpendicular distance from a point to a line or a surface. Gradient calculation step in which represents the variation of pixels over a steep of a straight line.

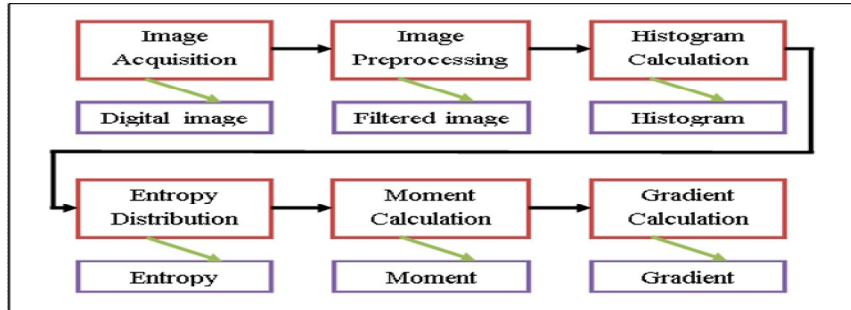


Figure1 The proposed approach

5. RESULTS AND ANALYSIS

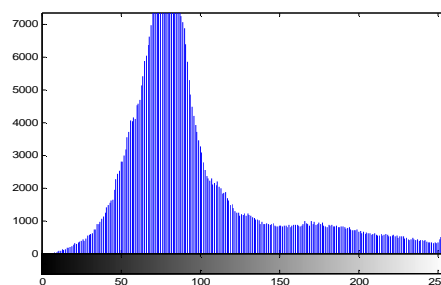
The system is implemented to track the variation of the bottles direction via the acquisition of many images in different positions. The obtained results of entropy, standard deviation and mean values are demonstrated in table1, In which we can mentioned that there are clear difference between the four tested images. Figure2 shows the image of four bottles at the same direction and its histogram, moment of the entropy and gradient of the moment, in figure (d) you can find that there are four peaks referred to four bottles. Figure3 shows the image of three bottles at the same direction and one bottle perpendicular in which you can indicate three peaks referred to three bottles. Figure4 shows the image of two bottles at the same direction and two bottles perpendicular in which you can indicate two peaks referred to two bottles. Figure5 shows the image of one bottle at the same direction and three bottles perpendicular in which you can indicate one peak referred to one bottle.

Table1 statistical measurements

Images	Entropy		Std. Dev.		Mean	
	Before entropy	After entropy	Before entropy	After entropy	Before entropy	After entropy
four bottles at the same direction	7.1908	0.0007	48.3470	3.8127	98.6526	3.8127
three bottles at the same direction and one bottle perpendicular	7.1308	0.0010	42.2151	1.3516	9.9893	3.6205
two bottles at the same direction and two bottles perpendicular	7.0856	0.0	45.3245	1.3746	76.9788	3.6526
one bottle at the same direction and three bottles perpendicular	7.1418	0.0029	48.3572	1.3534	73.5535	3.7523



(a) gray scale image



(b) histogram of the gray scale image

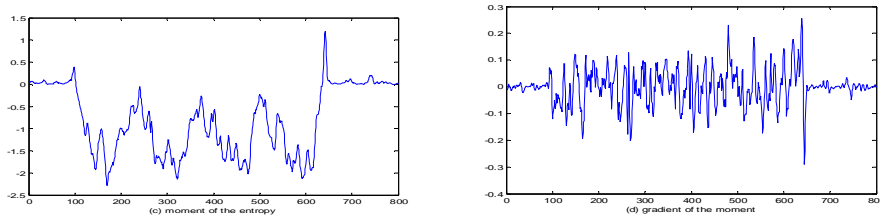


Figure 2 Four bottles at the same direction

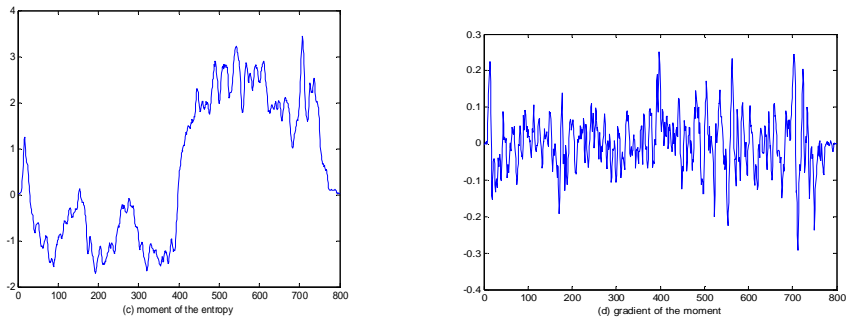
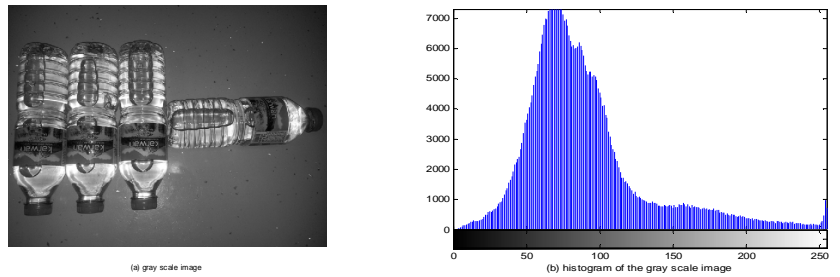


Figure 3 Three bottles at the same direction and one bottle perpendicular

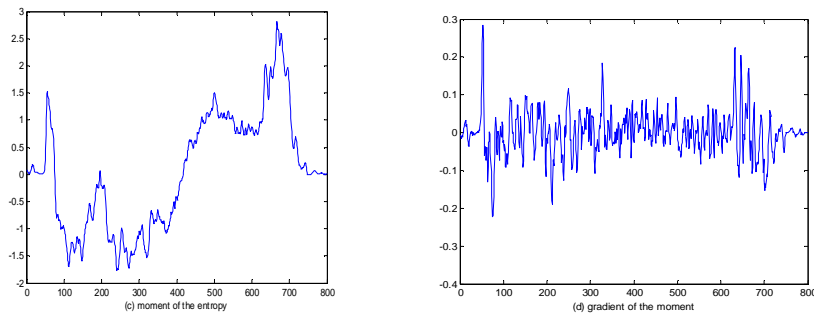
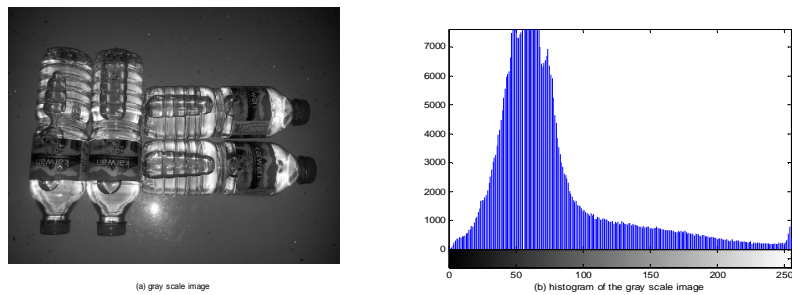


Figure 4 Two bottles at the same direction and two bottles perpendicular

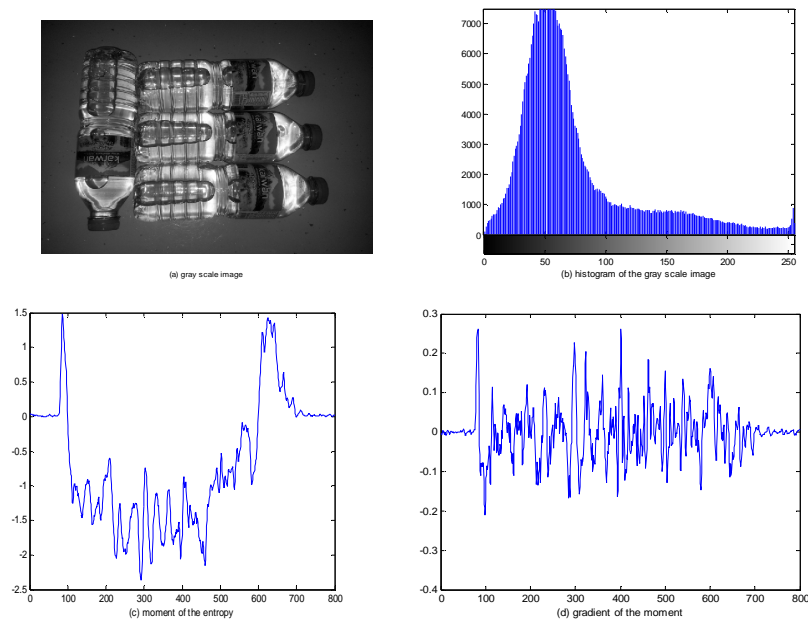


Figure 5 One bottle at the same direction and three bottles perpendicular

6. CONCLUSIONS

Object tracking and direction finding are concern an important part of digital image processing field. In this paper we designed and implemented an efficient information system approach to identify the directions of the objects in images that approach based on statistical measurements, histogram, entropy, moment and gradient. The implementation of this system indicated good results for object tracking and identification. Different directions of object are tested to improve the accuracy of this system.

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