

A

Proof

Proof of Theorem 3.1

Using Assumption 3.1, the closed-loop fuzzy system (3.5) can be expressed as follows:

$$\dot{x}(t) = \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left([A_i + B_{2_i} K_j] x(t) + \tilde{B}_{1_i} \tilde{w}(t) \right) \quad (\text{A.1})$$

where

$$\tilde{B}_{1_i} = [\delta I \quad I \quad \delta I \quad B_{1_i}],$$

and the disturbance $\tilde{w}(t)$ is

$$\tilde{w}(t) = \begin{bmatrix} \frac{1}{\delta} F(x(t), t) H_{1_i} x(t) \\ F(x(t), t) H_{2_i} w(t) \\ \frac{1}{\delta} F(x(t), t) H_{3_i} K_j x(t) \\ w(t) \end{bmatrix}. \quad (\text{A.2})$$

Let consider a Lyapunov function

$$V(x(t)) = \gamma x^T(t) Q x(t)$$

where $Q = P^{-1}$. Differentiate $V(x(t))$ along the closed-loop system (A.1) yields

$$\begin{aligned} \dot{V}(x(t)) &= \gamma \dot{x}^T(t) Q x(t) + \gamma x^T(t) Q \dot{x}(t) = \\ & \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\gamma x^T(t) (A_i + B_{2_i} K_j)^T Q x(t) + \gamma x^T(t) Q (A_i + B_{2_i} K_j) x(t) \right. \\ & \quad \left. + \gamma \tilde{w}^T(t) \tilde{B}_{1_i}^T Q x(t) + \gamma x^T(t) Q \tilde{B}_{1_i} \tilde{w}(t) \right). \end{aligned} \quad (\text{A.3})$$

Adding and subtracting $-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times [\tilde{w}^T(t) \tilde{w}(t)]$ to and from (A.3), we get

$$\begin{aligned}
\dot{V}(x(t)) &= \gamma \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [x^T(t) \tilde{w}^T(t)] \times \\
&\quad \left(\begin{array}{c} \left((A_i + B_{2_i} K_j)^T Q + Q(A_i + B_{2_i} K_j) \right) \\ + \frac{(\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j)^T (\tilde{C}_{1_m} + \tilde{D}_{12_m} K_n)}{\tilde{B}_{1_i}^\gamma Q} \end{array} \right) (*)^T \left[\begin{array}{c} x(t) \\ \tilde{w}(t) \end{array} \right] \\
&\quad - \tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)] \quad (\text{A.4})
\end{aligned}$$

where

$$\tilde{z}(t) = \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j [\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j] x(t) \quad (\text{A.5})$$

with $\tilde{C}_{1_i} = [\frac{\gamma \rho}{\delta} H_{1_i}^T \ 0 \ \sqrt{2} \lambda \rho H_{4_i}^T \ \sqrt{2} \lambda C_{1_i}^T]^T$ and $\tilde{D}_{12_i} = \begin{bmatrix} 0 & \frac{\gamma \rho}{\delta} H_{3_i}^T & \sqrt{2} \lambda \rho H_{6_i}^T \\ \sqrt{2} \lambda D_{12_i}^T \end{bmatrix}^T$. Pre and post multiply (3.7)-(3.8) by $\begin{pmatrix} Q & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & I \end{pmatrix}$ yields

$$\begin{pmatrix} (A_i + B_{2_i} K_i)^T Q + Q(A_i + B_{2_i} K_i) & (*)^T & (*)^T \\ \tilde{B}_{1_i}^T Q & -\gamma I & (*)^T \\ \tilde{C}_{1_i} + \tilde{D}_{12_i} K_i & 0 & -\gamma I \end{pmatrix} < 0, \quad (\text{A.6})$$

$i = 1, 2, \dots, r$, and

$$\begin{aligned}
&\left\{ \begin{array}{c} \left((A_i + B_{2_i} K_j)^T Q + Q(A_i + B_{2_i} K_j) & (*)^T & (*)^T \\ \tilde{B}_{1_i}^T Q & -\gamma I & (*)^T \\ \tilde{C}_{1_i} + \tilde{D}_{12_i} K_j & 0 & -\gamma I \end{array} \right) \\
&+ \left(\begin{array}{c} (A_j + B_{2_j} K_i)^T Q + Q(A_j + B_{2_j} K_i) & (*)^T & (*)^T \\ \tilde{B}_{1_j}^T Q & -\gamma I & (*)^T \\ \tilde{C}_{1_j} + \tilde{D}_{12_j} K_i & 0 & -\gamma I \end{array} \right) \end{array} \right\} < 0, \quad (\text{A.7})$$

$i < j \leq r$, respectively. Applying the Schur complement on (A.6)-(A.7) and rearranging them, then we have

$$\begin{pmatrix} \left((A_i + B_{2_i} K_i)^T Q + Q(A_i + B_{2_i} K_i) \right) \\ + \frac{(\tilde{C}_{1_i} + \tilde{D}_{12_i} K_i)^T (\tilde{C}_{1_i} + \tilde{D}_{12_i} K_i)}{\tilde{B}_{1_i}^\gamma Q} \end{pmatrix} (*)^T \begin{pmatrix} \\ \\ -\gamma I \end{pmatrix} < 0, \quad (\text{A.8})$$

$i = 1, 2, \dots, r$, and

$$\begin{aligned}
 & \left\{ \left(\left((A_i + B_{2_i} K_j)^T Q + Q(A_i + B_{2_i} K_j) \right) + \frac{(\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j)^T (\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j)}{\tilde{B}_{1_i}^\gamma Q} \right) (*)^T \right. \\
 & \left. - \gamma I \right) \\
 & + \left(\left((A_j + B_{2_j} K_i)^T Q + Q(A_j + B_{2_j} K_i) \right) + \frac{(\tilde{C}_{1_j} + \tilde{D}_{12_j} K_i)^T (\tilde{C}_{1_j} + \tilde{D}_{12_j} K_i)}{\tilde{B}_{1_j}^\gamma Q} \right) (*)^T \right) \left. \right\} < 0, \quad (\text{A.9})
 \end{aligned}$$

$i < j \leq r$, respectively. Using (A.8)-(A.9) and the fact that

$$\begin{aligned}
 & \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n M_{ij}^T N_{mn} \\
 & \leq \frac{1}{2} \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j [M_{ij}^T M_{ij} + N_{ij} N_{ij}^T], \quad (\text{A.10})
 \end{aligned}$$

it is obvious that we have

$$\left(\left((A_i + B_{2_i} K_j)^T Q + Q(A_i + B_{2_i} K_j) \right) + \frac{(\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j)^T (\tilde{C}_{1_i} + \tilde{D}_{12_i} K_j)}{\tilde{B}_{1_i}^\gamma Q} \right) (*)^T - \gamma I < 0 \quad (\text{A.11})$$

where $i, j = 1, 2, \dots, r$. Since (A.11) is less than zero and the fact that $\mu_i \geq 0$ and $\sum_{i=1}^r \mu_i = 1$, then (A.4) becomes

$$\dot{V}(x(t)) \leq -\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)]. \quad (\text{A.12})$$

Integrate both sides of (A.12) yields

$$\begin{aligned}
 & \int_0^{T_f} \dot{V}(x(t)) dt \leq \int_0^{T_f} \left[-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times \right. \\
 & \quad \left. \tilde{w}^T(t) \tilde{w}(t) \right] dt \\
 & V(x(T_f)) - V(x(0)) \leq \int_0^{T_f} \left[-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times \right. \\
 & \quad \left. \tilde{w}^T(t) \tilde{w}(t) \right] dt.
 \end{aligned}$$

Using the fact that $x(0) = 0$ and $V(x(T_f)) \geq 0$ for all $T_f \neq 0$, we get

$$\int_0^{T_f} \tilde{z}^T(t) \tilde{z}(t) dt \leq \gamma^2 \left[\int_0^{T_f} \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)] dt \right]. \quad (\text{A.13})$$

Putting $\tilde{z}(t)$ and $\tilde{w}(t)$ respectively given in (A.5) and (A.2) into (A.13) and using the fact that $\|F(x(t), t)\| \leq \rho$, $\lambda^2 = \left(1 + \rho^2 \sum_{i=1}^r \sum_{j=1}^r [\|H_{2_i}^T H_{2_j}\|]\right)$ and (A.10), we have

$$\begin{aligned} & \int_0^{T_f} \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 x^T(t) [C_{1_i} + D_{12_i} K_j]^T [C_{1_i} + D_{12_i} K_j] x(t) \right. \\ & \quad \left. + 2\lambda^2 \rho^2 x^T(t) [H_{4_i} + H_{6_i} K_j]^T [H_{4_i} + H_{6_i} K_j] x(t) \right) dt \\ & \leq \gamma^2 \lambda^2 \left[\int_0^{T_f} w^T(t) w(t) dt \right]. \end{aligned} \quad (\text{A.14})$$

Adding and subtracting

$$\begin{aligned} \lambda^2 z^T(t) z(t) &= \lambda^2 \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(x^T(t) [C_{1_i} + F(x(t), t) H_{4_i} + D_{12_i} K_j \right. \\ & \quad \left. + F(x(t), t) H_{6_i} K_j]^T [C_{1_i} + F(x(t), t) H_{4_i} + D_{12_i} K_j \right. \\ & \quad \left. F(x(t), t) H_{6_i} K_j] x(t) \right) \end{aligned}$$

to and from (A.14), one obtains

$$\begin{aligned} & \int_0^{T_f} \left\{ \lambda^2 z^T(t) z(t) + \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 x^T(t) [C_{1_i} + D_{12_i} K_j]^T \times \right. \right. \\ & \quad [C_{1_i} + D_{12_i} K_j] x(t) + 2\lambda^2 \rho^2 x^T(t) [H_{4_i} + H_{6_i} K_j]^T [H_{4_i} + H_{6_i} K_j] x(t) \\ & \quad - \lambda^2 x^T(t) [C_{1_i} + F(x(t), t) H_{4_i} \\ & \quad + D_{12_i} K_j + F(x(t), t) H_{6_i} K_j]^T [C_{1_i} + F(x(t), t) H_{4_i} + D_{12_i} K_j \\ & \quad \left. \left. + F(x(t), t) H_{6_i} K_j] x(t) \right) \right\} dt \leq \gamma^2 \lambda^2 \left[\int_0^{T_f} w^T(t) w(t) dt \right]. \end{aligned} \quad (\text{A.15})$$

Using the triangular inequality and the fact that $\|F(x(t), t)\| \leq \rho$, we have

$$\begin{aligned} & \lambda^2 \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(x^T(t) [C_{1_i} + F(x(t), t) H_{4_i} + D_{12_i} K_j + F(x(t), t) H_{6_i} K_j]^T \right. \\ & \quad \left. \times [C_{1_i} + F(x(t), t) H_{4_i} + D_{12_i} K_j + F(x(t), t) H_{6_i} K_j] x(t) \right) \\ & \leq \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 x^T(t) [C_{1_i} + D_{12_i} K_j]^T [C_{1_i} + D_{12_i} K_j] x(t) \right. \\ & \quad \left. + 2\lambda^2 \rho^2 x^T(t) [H_{4_i} + H_{6_i} K_j]^T [H_{4_i} + H_{6_i} K_j] x(t) \right). \end{aligned} \quad (\text{A.16})$$

Using (A.16) on (A.15), we obtain

$$\int_0^{T_f} z^T(t)z(t) \leq \gamma^2 \int_0^{T_f} w^T(t)w(t) dt. \tag{A.17}$$

Hence, the inequality (3.3) holds. ■

Proof of Lemma 3.1

The state space form of the fuzzy system model (3.1) with the controller (3.13) is given by

$$\begin{aligned} \dot{\tilde{x}}(t) &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(A_{cl}^{ij} \tilde{x}(t) + B_{cl}^{ij} \tilde{w}(t) \right) \\ \tilde{z}(t) &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j C_{cl}^{ij} \tilde{x}(t) \end{aligned} \tag{A.18}$$

where $\tilde{x}(t) = [x^T(t) \hat{x}^T(t)]^T$ and the matrix functions A_{cl}^{ij} , B_{cl}^{ij} and C_{cl}^{ij} are defined in Lemma 1 and the disturbance is

$$\tilde{w}(t) = \begin{bmatrix} \frac{1}{\delta} F(x(t), t) H_{1_i} x(t) \\ F(x(t), t) H_{2_i} w(t) \\ \frac{1}{\delta} F(x(t), t) H_{3_i} \hat{C}_j \hat{x}(t) \\ \frac{1}{\delta} F(x(t), t) H_{5_i} x(t) \\ w(t) \\ F(x(t), t) H_{7_i} w(t) \end{bmatrix}. \tag{A.19}$$

Let choose a Lyapunov function

$$V(\tilde{x}(t)) = \tilde{x}^T(t) Q \tilde{x}(t), \tag{A.20}$$

where $Q = P^{-1}$. Differentiate $V(\tilde{x}(t))$ along the closed-loop system (A.18) yields

$$\begin{aligned} \dot{V}(\tilde{x}(t)) &= \dot{\tilde{x}}^T(t) Q \tilde{x}(t) + \tilde{x}^T(t) Q \dot{\tilde{x}}(t) \\ &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\tilde{x}^T(t) (A_{cl}^{ij})^T Q \tilde{x}(t) + \tilde{x}^T(t) Q A_{cl}^{ij} \tilde{x}(t) \right. \\ &\quad \left. + \tilde{w}^T(t) (B_{cl}^{ij})^T Q \tilde{x}(t) + \tilde{x}^T(t) Q B_{cl}^{ij} \tilde{w}(t) \right). \end{aligned} \tag{A.21}$$

Add and subtract

$$-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}(t)^T \tilde{w}(t)]$$

to and from (A.21) yields

$$\begin{aligned}
\dot{V}(\tilde{x}(t)) &= \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{x}^T(t) \tilde{w}^T(t)] \\
&\quad \left(\begin{array}{cc} \left((A_{cl}^{ij})^T Q + Q A_{cl}^{ij} \right) (*)^T & (*)^T \\ + (C_{cl}^{ij})^T C_{cl}^{mn} & -\gamma^2 I \end{array} \right) \begin{bmatrix} \tilde{x}(t) \\ \tilde{w}(t) \end{bmatrix} \\
&\quad - \tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)]. \quad (\text{A.22})
\end{aligned}$$

Now suppose there exists a matrix $P > 0$ such that (3.15) holds, i.e.,

$$\left(\begin{array}{cc} A_{cl}^{ij} P + P (A_{cl}^{ij})^T & (*)^T & (*)^T \\ (B_{cl}^{ij})^T & -\gamma^2 I & (*)^T \\ C_{cl}^{ij} P & 0 & -I \end{array} \right) < 0. \quad (\text{A.23})$$

Pre and post multiply (A.23) by $\begin{pmatrix} Q & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & I \end{pmatrix}$ yields

$$\left(\begin{array}{cc} (A_{cl}^{ij})^T Q + Q A_{cl}^{ij} & (*)^T & (*)^T \\ (B_{cl}^{ij})^T Q & -\gamma^2 I & (*)^T \\ C_{cl}^{ij} & 0 & -I \end{array} \right) < 0. \quad (\text{A.24})$$

The Schur complement of (A.24) is

$$\left(\begin{array}{cc} (A_{cl}^{ij})^T Q + Q A_{cl}^{ij} + (C_{cl}^{ij})^T C_{cl}^{ij} & (*)^T \\ (B_{cl}^{ij})^T & -\gamma^2 I \end{array} \right) < 0. \quad (\text{A.25})$$

Using (A.25) and the fact in (A.10) together with the fact that $\mu_i \geq 0$ and $\sum_{i=1}^r \mu_i = 1$, then (A.22) becomes

$$\dot{V}(\tilde{x}(t)) \leq -\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)]. \quad (\text{A.26})$$

Integrate both sides of (A.26) yields

$$\begin{aligned}
\int_0^{T_f} \dot{V}(\tilde{x}(t)) dt &\leq \int_0^{T_f} \left(-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times \right. \\
&\quad \left. [\tilde{w}^T(t) \tilde{w}(t)] \right) dt \\
V(\tilde{x}(T_f)) - V(\tilde{x}(0)) &\leq \int_0^{T_f} \left(-\tilde{z}^T(t) \tilde{z}(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times \right. \\
&\quad \left. [\tilde{w}^T(t) \tilde{w}(t)] \right) dt.
\end{aligned}$$

Using the fact that $\check{x}(0) = 0$ and $V(\check{x}(T_f)) > 0$ for all $T_f \neq 0$, we have

$$\int_0^{T_f} \check{z}^T(t)\check{z}(t)dt \leq \gamma^2 \left[\int_0^{T_f} \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\tilde{w}(t)] \right] dt. \quad (\text{A.27})$$

Putting $\check{z}(t)$ and $\tilde{w}(t)$ respectively given in (A.18) and (A.19) into (A.27) and using the fact that $\|F(x(t), t)\| \leq \rho$, $\lambda^2 = \left(1 + \rho^2 \sum_{i=1}^r \sum_{j=1}^r \left[\|H_{2_i}^T H_{2_j}\| + \|H_{7_i}^T H_{7_j}\| \right] \right)$ and (A.10), we have

$$\begin{aligned} & \int_0^{T_f} \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 \check{x}^T(t) [C_{1_i} \ D_{12_i} \hat{C}_j]^T [C_{1_i} \ D_{12_i} \hat{C}_j] \check{x}(t) \right. \\ & \left. + 2\lambda^2 \rho^2 \check{x}^T(t) [H_{4_i} \ H_{6_i} \hat{C}_j]^T [H_{4_i} \ H_{6_i} \hat{C}_j] \check{x}(t) \right) dt \leq \gamma^2 \lambda^2 \left[\int_0^{T_f} w^T(t)w(t) dt \right]. \end{aligned} \quad (\text{A.28})$$

Adding and subtracting

$$\begin{aligned} \lambda^2 z^T(t)z(t) &= \lambda^2 \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\check{x}^T(t) \left[C_{1_i} + F(x(t), t)H_{4_i} \ D_{12_i} \hat{C}_j \right. \right. \\ & \quad \left. \left. + F(x(t), t)H_{6_i} \hat{C}_j \right]^T \left[C_{1_i} + F(x(t), t)H_{4_i} \ D_{12_i} \hat{C}_j \right. \right. \\ & \quad \left. \left. + F(x(t), t)H_{6_i} \hat{C}_j \right] \check{x}(t) \right) \end{aligned}$$

to and from (A.28), one obtains

$$\begin{aligned} & \int_0^{T_f} \left\{ \lambda^2 z^T(t)z(t) + \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 \check{x}^T(t) [C_{1_i} \ D_{12_i} \hat{C}_j]^T [C_{1_i} \ D_{12_i} \hat{C}_j] \check{x}(t) \right. \right. \\ & \quad \left. \left. + 2\lambda^2 \rho^2 \check{x}^T(t) [H_{4_i} \ H_{6_i} \hat{C}_j]^T [H_{4_i} \ H_{6_i} \hat{C}_j] \check{x}(t) \right. \right. \\ & \quad \left. \left. - \lambda^2 \check{x}^T(t) [C_{1_i} + F(x(t), t)H_{4_i} \ D_{12_i} \hat{C}_j + F(x(t), t)H_{6_i} \hat{C}_j]^T \times \right. \right. \\ & \quad \left. \left. [C_{1_i} + F(x(t), t)H_{4_i} \ D_{12_i} \hat{C}_j + F(x(t), t)H_{6_i} \hat{C}_j] \check{x}(t) \right) \right\} dt \\ & \leq \gamma^2 \lambda^2 \left[\int_0^{T_f} w^T(t)w(t) dt \right]. \end{aligned} \quad (\text{A.29})$$

Using the triangular inequality and the fact that $\|F(x(t), t)\| \leq \rho$, we have

$$\begin{aligned}
& \lambda^2 \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\tilde{x}^T(t) \left[C_{1_i} + F(x(t), t) H_{4_i} \quad D_{12_i} \hat{C}_j + F(x(t), t) H_{6_i} \hat{C}_j \right]^T \times \right. \\
& \left. \left[C_{1_i} + F(x(t), t) H_{4_i} \quad D_{12_i} \hat{C}_j + F(x(t), t) H_{6_i} \hat{C}_j \right] \tilde{x}(t) \right) \\
& \leq \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(2\lambda^2 \tilde{x}^T(t) \left[C_{1_i} \quad D_{12_i} \hat{C}_j \right]^T \left[C_{1_i} \quad D_{12_i} \hat{C}_j \right] \tilde{x}(t) \right. \\
& \left. + 2\lambda^2 \rho^2 \tilde{x}^T(t) \left[H_{4_i} \quad H_{6_i} \hat{C}_j \right]^T \left[H_{4_i} \quad H_{6_i} \hat{C}_j \right] \tilde{x}(t) \right). \tag{A.30}
\end{aligned}$$

Using (A.30) on (A.29), we obtain

$$\int_0^{T_f} z^T(t) z(t) \leq \gamma^2 \int_0^{T_f} w^T(t) w(t) dt. \tag{A.31}$$

Hence, the inequality (3.3) is guaranteed. \blacksquare

Proof of Theorem 5.1

The closed-loop state space form of the fuzzy system model (5.1) with the controller (5.6) is given by

$$\begin{aligned}
\dot{x}(t) = & \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left([A_i(\iota) + B_{2_i}(\iota) K_j(\iota)] x(t) + [\Delta A_i(\iota) + \Delta B_{2_i}(\iota) K_j(\iota)] x(t) \right. \\
& \left. + [B_{1_i}(\iota) + \Delta B_{1_i}(\iota)] w(t) \right), \quad x(0) = 0, \tag{A.32}
\end{aligned}$$

or in a more compact form

$$\dot{x}(t) = \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left([A_i(\iota) + B_{2_i}(\iota) K_j(\iota)] x(t) + \tilde{B}_{1_i}(\iota) \mathcal{R}(\iota) \tilde{w}(t) \right) \tag{A.33}$$

where

$$\tilde{B}_{1_i}(\iota) = [I \ I \ I \ B_{1_i}(\iota)] \tag{A.34}$$

$$\tilde{w}(t) = \mathcal{R}^{-1}(\iota) \begin{bmatrix} F(x(t), \iota, t) H_{1_i}(\iota) x(t) \\ F(x(t), \iota, t) H_{2_i}(\iota) w(t) \\ F(x(t), \iota, t) H_{3_i}(\iota) K_j(\iota) x(t) \\ w(t) \end{bmatrix}. \tag{A.35}$$

Consider a Lyapunov functional candidate as follows:

$$V(x(t), \iota) = \gamma x^T(t) Q(\iota) x(t), \quad \forall \iota \in \mathcal{S}. \tag{A.36}$$

Note that $Q(\iota)$ is constant for each ι . For this choice, we have $V(0, \iota_0) = 0$ and $V(x(t), \iota) \rightarrow \infty$ only when $\|x(t)\| \rightarrow \infty$.

Now let consider the weak infinitesimal operator $\tilde{\Delta}$ of the joint process $\{(x(t), \iota), t \geq 0\}$, which is the stochastic analog of the deterministic derivative. $\{(x(t), \iota), t \geq 0\}$ is a Markov process with infinitesimal operator given by [80],

$$\begin{aligned} \tilde{\Delta}V(x(t), \iota) &= \gamma \dot{x}^T(t)Q(\iota)x(t) + \gamma x^T(t)Q(\iota)\dot{x}(t) + \gamma x^T(t) \sum_{k=1}^s \lambda_{ik}Q(k)x(t) \\ &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\gamma x^T(t)Q(\iota) [(A_i(\iota) + B_{2_i}(\iota)K_j(\iota))] x(t) \right. \\ &\quad + \gamma x^T(t) [A_i(\iota) + B_{2_i}(\iota)K_j(\iota)]^T Q(\iota)x(t) \\ &\quad + \gamma x^T(t)Q(\iota)\tilde{B}_{1_i}(\iota)\mathcal{R}(\iota)\tilde{w}(t) \\ &\quad \left. + \gamma \tilde{w}^T(t)\mathcal{R}(\iota)\tilde{B}_{1_i}^T(\iota)Q(\iota)x(t) + \gamma x^T(t) \sum_{k=1}^s \lambda_{ik}Q(k)x(t) \right) \quad (\text{A.37}) \end{aligned}$$

Adding and subtracting

$$-\aleph^2(\iota)z^T(t)z(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\mathcal{R}(\iota)\tilde{w}(t)]$$

to and from (A.37), we get

$$\begin{aligned} \tilde{\Delta}V(x(t), \iota) &= -\aleph^2(\iota)z^T(t)z(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\mathcal{R}(\iota)\tilde{w}(t)] \\ &\quad + \aleph^2(\iota)z^T(t)z(t) + \gamma \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \times \\ &\quad \left(\begin{array}{c} \left(\begin{array}{c} [A_i(\iota) + B_{2_i}(\iota)K_j(\iota)]^T Q(\iota) \\ + Q(\iota)[A_i(\iota) + B_{2_i}(\iota)K_j(\iota)] \\ + \sum_{k=1}^s \lambda_{ik}Q(k) \end{array} \right) \\ \mathcal{R}(\iota)\tilde{B}_{1_i}^T(\iota)Q(\iota) \end{array} \right) \begin{array}{c} (*)^T \\ -\gamma\mathcal{R}(\iota) \end{array} \right) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}. \quad (\text{A.38}) \end{aligned}$$

Now let us consider the following terms:

$$\begin{aligned} \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\mathcal{R}(\iota)\tilde{w}(t)] &= \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \\ &\times \begin{bmatrix} F(x(t), \iota, t)H_{1_i}(\iota)x(t) \\ F(x(t), \iota, t)H_{2_i}(\iota)w(t) \\ F(x(t), \iota, t)H_{3_i}(\iota)K_j(\iota)x(t) \\ w(t) \end{bmatrix}^T \mathcal{R}^{-1}(\iota) \begin{bmatrix} F(x(t), \iota, t)H_{1_m}(\iota)x(t) \\ F(x(t), \iota, t)H_{2_m}(\iota)w(t) \\ F(x(t), \iota, t)H_{3_m}(\iota)K_n(\iota)x(t) \\ w(t) \end{bmatrix} \\ &\leq \frac{\rho^2(\iota)\gamma^2}{\delta(\iota)} \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n x^T(t) \left\{ H_{1_i}^T(\iota)H_{1_m}(\iota) \right. \\ &\quad \left. + K_j^T(\iota)H_{3_i}^T(\iota)H_{3_m}(\iota)K_n(\iota) \right\} x(t) + \aleph^2(\iota)\gamma^2 w^T(t)w(t) \quad (\text{A.39}) \end{aligned}$$

and

$$\begin{aligned}
\aleph^2(\iota)z^T(t)z(t) &= \aleph^2(\iota) \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n x^T(t) \left[C_{1_i}(\iota) + \right. \\
&\quad \left. F(x(t), \iota, t)H_{4_i}(\iota) + D_{12_i}(\iota)K_j(\iota) + F(x(t), \iota, t)H_{6_i}(\iota)K_j(\iota) \right]^T \\
&\quad \times \left[C_{1_m}(\iota) + F(x(t), \iota, t)H_{4_m}(\iota) \right. \\
&\quad \left. + D_{12_m}(\iota)K_n(\iota) + F(x(t), \iota, t)H_{6_m}(\iota)K_n(\iota) \right] x(t) \\
&\leq 2\aleph^2(\iota) \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n x^T(t) \left\{ \right. \\
&\quad \left. [C_{1_i}(\iota) + D_{12_i}(\iota)K_j(\iota)]^T [C_{1_m}(\iota) + D_{12_m}(\iota)K_n(\iota)] + \right. \\
&\quad \left. \rho^2(\iota) [H_{4_i}(\iota) + H_{6_i}(\iota)K_j(\iota)]^T \times \right. \\
&\quad \left. [H_{4_m}(\iota) + H_{6_m}(\iota)K_n(\iota)] \right\} x(t) \tag{A.40}
\end{aligned}$$

where $\aleph(\iota) = \left(1 + \rho^2(\iota) \sum_{i=1}^r \sum_{j=1}^r [\|H_{2_i}^T(\iota)H_{2_j}(\iota)\|]\right)^{\frac{1}{2}}$. Hence,

$$\begin{aligned}
&\gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\mathcal{R}(\iota)\tilde{w}(t)] + \aleph^2(\iota)z^T(t)z(t) \\
&\leq \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \left(x^T(t) \left[\tilde{C}_{1_i}(\iota) + \tilde{D}_{12_i}(\iota)K_j(\iota) \right]^T \mathcal{R}^{-1}(\iota) \times \right. \\
&\quad \left. \left[\tilde{C}_{1_m}(\iota) + \tilde{D}_{12_m}(\iota)K_n(\iota) \right] x(t) \right) + \aleph^2(\iota)\gamma^2 w^T(t)w(t) \tag{A.41}
\end{aligned}$$

where

$$\begin{aligned}
\tilde{C}_{1_i}(\iota) &= [\gamma\rho(\iota)H_{1_i}^T(\iota) \sqrt{2}\aleph(\iota)\rho(\iota)H_{4_i}^T(\iota) \ 0 \ \sqrt{2}\aleph(\iota)C_{1_i}^T(\iota)]^T \\
\tilde{D}_{12_i}(\iota) &= [0 \ \sqrt{2}\aleph(\iota)\rho(\iota)H_{6_i}^T(\iota) \ \gamma\rho(\iota)H_{3_i}^T(\iota) \ \sqrt{2}\aleph(\iota)D_{12_i}^T(\iota)]^T.
\end{aligned}$$

Substituting (A.41) into (A.38), we have

$$\begin{aligned}
\tilde{\Delta}V(x(t), \iota) &\leq -\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t) \\
&\quad + \gamma \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \Phi_{ijmn}(\iota) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \tag{A.42}
\end{aligned}$$

where

$$\Phi_{ijmn}(\iota) = \left(\begin{array}{c} \left(\begin{array}{c} (A_i(\iota) + B_{2_i}(\iota)K_j(\iota))^T Q(\iota) \\ + Q(\iota) [A_i(\iota) + B_{2_i}(\iota)K_j(\iota)] \\ + \frac{1}{\gamma} [\tilde{C}_{1_i}(\iota) + \tilde{D}_{12_i}(\iota)K_j(\iota)]^T \times \\ \mathcal{R}^{-1}(\iota) [\tilde{C}_{1_m}(\iota) + \tilde{D}_{12_m}(\iota)K_n(\iota)] \\ + \sum_{k=1}^s \lambda_{ik} Q(k) \\ \mathcal{R}(\iota) \tilde{B}_{1_i}^T(\iota) Q(\iota) \end{array} \right) \\ (*)^T \\ -\gamma \mathcal{R}(\iota) \end{array} \right). \quad (\text{A.43})$$

Using the fact

$$\sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n M_{ij}^T(\iota) N_{mn}(\iota) \leq \frac{1}{2} \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j [M_{ij}^T(\iota) M_{ij}(\iota) + N_{ij}(\iota) N_{ij}^T(\iota)],$$

we can rewrite (A.42) as follows:

$$\begin{aligned} \tilde{\Delta}V(x(t), \iota) &\leq -\aleph^2(\iota) z^T(t) z(t) + \gamma^2 \aleph^2(\iota) w^T(t) w(t) \\ &\quad + \gamma \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \Phi_{ij}(\iota) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \\ &= -\aleph^2(\iota) z^T(t) z(t) + \gamma^2 \aleph^2(\iota) w^T(t) w(t) \\ &\quad + \gamma \sum_{i=1}^r \mu_i^2 \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \Phi_{ii}(\iota) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \\ &\quad + \gamma \sum_{i=1}^r \sum_{i < j}^r \mu_i \mu_j \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T (\Phi_{ij}(\iota) + \Phi_{ji}(\iota)) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \end{aligned} \quad (\text{A.44})$$

where

$$\Phi_{ij}(\iota) = \left(\begin{array}{c} \left(\begin{array}{c} (A_i(\iota) + B_{2_i}(\iota)K_j(\iota))^T Q(\iota) \\ + Q(\iota) (A_i(\iota) + B_{2_i}(\iota)K_j(\iota)) \\ + \frac{1}{\gamma} [\tilde{C}_{1_i}(\iota) + \tilde{D}_{12_i}(\iota)K_j(\iota)]^T \times \\ \mathcal{R}^{-1}(\iota) [\tilde{C}_{1_i}(\iota) + \tilde{D}_{12_i}(\iota)K_j(\iota)] \\ + \sum_{k=1}^s \lambda_{ik} Q(k) \\ \mathcal{R}(\iota) \tilde{B}_{1_i}^T(\iota) Q(\iota) \end{array} \right) \\ (*)^T \\ -\gamma \mathcal{R}(\iota) \end{array} \right). \quad (\text{A.45})$$

Pre and post multiplying (A.45) by

$$\Xi(\iota) = \begin{pmatrix} P(\iota) & 0 \\ 0 & I \end{pmatrix},$$

with $P(\iota) = Q^{-1}(\iota)$, we obtain

$$\Xi(\iota)\Phi_{ij}(\iota)\Xi(\iota) = \begin{pmatrix} \begin{pmatrix} P(\iota)A_i^T(\iota) + Y_j^T(\iota)B_{2_i}^T(\iota) \\ + A_i(\iota)P(\iota) + B_{2_i}(\iota)Y_j(\iota) \\ + \frac{1}{\gamma} \left[\tilde{C}_{1_i}(\iota)P(\iota) + \tilde{D}_{12_i}(\iota)Y_j(\iota) \right]^T \mathcal{R}^{-1}(\iota) \times \\ \left[\tilde{C}_{1_i}(\iota)P(\iota) + \tilde{D}_{12_i}(\iota)Y_j(\iota) \right] \\ + \sum_{k=1}^s \lambda_{i,k} P(\iota)P^{-1}(k)P(\iota) \\ \mathcal{R}(\iota)\tilde{B}_{1_i}^T(\iota) \end{pmatrix} & (*)^T \\ & -\gamma\mathcal{R}(\iota) \end{pmatrix}. \quad (\text{A.46})$$

Note that (A.46) is the Schur complement of $\Psi_{ij}(\iota)$ defined in (5.11). Using (5.9)-(5.10), we learn that

$$\Phi_{ii}(\iota) < 0 \quad (\text{A.47})$$

$$\Phi_{ij}(\iota) + \Phi_{ji}(\iota) < 0. \quad (\text{A.48})$$

Following from (A.44), (A.47) and (A.48), we know that

$$\tilde{\Delta}V(x(t), \iota) < -\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t). \quad (\text{A.49})$$

Applying the operator $\mathbf{E}[\int_0^{T_f} (\cdot) dt]$ on both sides of (A.49), we obtain

$$\mathbf{E} \left[\int_0^{T_f} \tilde{\Delta}V(x(t), \iota) dt \right] < \mathbf{E} \left[\int_0^{T_f} (-\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t)) dt \right]. \quad (\text{A.50})$$

From the Dynkin's formula [75], it follows that

$$\mathbf{E} \left[\int_0^{T_f} \tilde{\Delta}V(x(t), \iota) dt \right] = \mathbf{E}[V(x(T_f), \iota(T_f))] - \mathbf{E}[V(x(0), \iota(0))]. \quad (\text{A.51})$$

Substitute (A.51) into (A.50) yields

$$0 < \mathbf{E} \left[\int_0^{T_f} (-\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t)) dt \right] - \mathbf{E}[V(x(T_f), \iota(T_f))] + \mathbf{E}[V(x(0), \iota(0))].$$

Using (A.49) and the fact that $V(x(0), \iota(0)) = 0$ and $V(x(T_f), \iota(T_f)) > 0$, we have

$$\mathbf{E} \left[\int_0^{T_f} \left\{ z^T(t)z(t) - \gamma^2 w^T(t)w(t) \right\} dt \right] < 0. \quad (\text{A.52})$$

Hence, the inequality (5.5) holds. This completes the proof of Theorem 6. ■

Proof of Lemma 5.1

The closed-loop state space form of the fuzzy system model (5.1) with the controller (5.24) is given by

$$\begin{aligned}\dot{\tilde{x}}(t) &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(A_{cl}^{ij}(\iota) \tilde{x}(t) + B_{cl}^{ij}(\iota) \tilde{w}(t) \right) \\ \dot{\tilde{z}}(t) &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j C_{cl}^{ij}(\iota) \tilde{x}(t)\end{aligned}\tag{A.53}$$

where $\tilde{x}(t) = [x^T(t) \ \hat{x}^T(t)]^T$ and the matrix functions $A_{cl}^{ij}(\iota)$, $B_{cl}^{ij}(\iota)$ and $C_{cl}^{ij}(\iota)$ are defined in Lemma 3 and the disturbance is

$$\tilde{w}(t) = \begin{bmatrix} \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{1_i}(\iota) x(t) \\ F(x(t), \iota, t) H_{2_i}(\iota) w(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{3_i}(\iota) \hat{C}_j(\iota) \hat{x}(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{5_i}(\iota) x(t) \\ w(t) \\ F(x(t), \iota, t) H_{7_i}(\iota) w(t) \end{bmatrix}.$$

Let choose a stochastic Lyapunov function

$$V(\tilde{x}(t), \iota) = \tilde{x}^T(t) P(\iota) \tilde{x}(t) \quad \forall \iota \in \mathcal{S}\tag{A.54}$$

where $P(\iota)$ is a constant positive definite matrix for each ι . For this choice, we have $V(0, \iota_0) = 0$ and $V(\tilde{x}(t), \iota) \rightarrow \infty$ only when $\|\tilde{x}(t)\| \rightarrow \infty$.

Consider the weak infinitesimal operator $\tilde{\Delta}$ of the joint process $\{(\tilde{x}(t), \iota), t \geq 0\}$, which is the stochastic analog of the deterministic derivative. $\{(\tilde{x}(t), \iota), t \geq 0\}$ is a Markov process with infinitesimal operator given by [80],

$$\begin{aligned}\tilde{\Delta}V(\tilde{x}(t), \iota) &= \dot{\tilde{x}}^T(t) P(\iota) \tilde{x}(t) + \tilde{x}^T(t) P(\iota) \dot{\tilde{x}}(t) + \tilde{x}^T(t) \sum_{k=1}^s \lambda_{\iota k} P(k) \tilde{x}^T(t) \\ &= \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \left(\tilde{x}^T(t) (A_{cl}^{ij}(\iota))^T P(\iota) \tilde{x}(t) + \tilde{x}^T(t) P(\iota) A_{cl}^{ij}(\iota) \tilde{x}(t) \right. \\ &\quad \left. + \tilde{w}^T(t) (B_{cl}^{ij}(\iota))^T P(\iota) \tilde{x}(t) + \tilde{x}^T(t) P(\iota) B_{cl}^{ij}(\iota) \tilde{w}(t) \right. \\ &\quad \left. + \tilde{x}^T(t) \sum_{k=1}^s \lambda_{\iota k} P(k) \tilde{x}^T(t) \right).\end{aligned}\tag{A.55}$$

Adding and subtracting

$$-\mathcal{N}^2(\iota) z^T(t) z(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)]$$

to and from (A.55), we get

$$\begin{aligned}
\tilde{\Delta}V(x(t), \iota) &= -\aleph^2(\iota)z^T(t)z(t) + \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\tilde{w}(t)] \\
&\quad + \aleph^2(\iota)z^T(t)z(t) + \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \left[\begin{array}{c} \tilde{x}(t) \\ \tilde{w}(t) \end{array} \right]^T \times \\
&\quad \left(\left(\begin{array}{c} (A_{cl}^{ij}(\iota))^T P(\iota) + P(\iota) A_{cl}^{ij}(\iota) \\ + \sum_{k=1}^s \lambda_{ik} P(k) \\ (B_{cl}^{ij}(\iota))^T P(\iota) \end{array} \right) \begin{array}{c} (*)^T \\ -\gamma^2 I \end{array} \right) \left[\begin{array}{c} \tilde{x}(t) \\ \tilde{w}(t) \end{array} \right]. \quad (\text{A.56})
\end{aligned}$$

Now let us consider the following terms:

$$\begin{aligned}
\gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t)\tilde{w}(t)] &= \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \times \\
&\quad \left[\begin{array}{c} \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{1_i}(\iota) x(t) \\ F(x(t), \iota, t) H_{2_i}(\iota) w(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{3_i}(\iota) \hat{C}_j(\iota) \hat{x}(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{5_i}(\iota) x(t) \\ w(t) \\ F(x(t), \iota, t) H_{7_i}(\iota) w(t) \end{array} \right]^T \left[\begin{array}{c} \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{1_m}(\iota) x(t) \\ F(x(t), \iota, t) H_{2_m}(\iota) w(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{3_m}(\iota) \hat{C}_n(\iota) \hat{x}(t) \\ \frac{1}{\delta(\iota)} F(x(t), \iota, t) H_{5_m}(\iota) x(t) \\ w(t) \\ F(x(t), \iota, t) H_{7_m}(\iota) w(t) \end{array} \right] \\
&\leq \frac{\gamma^2 \rho^2(\iota)}{\delta^2(\iota)} \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \tilde{x}^T(t) \times \\
&\quad \left[\left(\begin{array}{c} H_{1_i}^T(\iota) H_{1_m}(\iota) \\ + H_{5_i}^T(\iota) H_{5_m}(\iota) \end{array} \right) \left(\begin{array}{c} \hat{C}_j^T(\iota) H_{3_i}^T(\iota) \times \\ H_{3_m}(\iota) \hat{C}_n(\iota) \end{array} \right) \right] \tilde{x}(t) + \aleph^2(\iota) \gamma^2 w^T(t) w(t) \quad (\text{A.57})
\end{aligned}$$

and

$$\begin{aligned}
\aleph^2(\iota)z^T(t)z(t) &= \aleph^2(\iota) \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \tilde{x}^T(t) \times \\
&\quad \left[\begin{array}{c} C_{1_i}(\iota) + F(x(t), \iota, t) H_{4_i}(\iota) \quad D_{12_i}(\iota) \hat{C}_j(\iota) + F(x(t), \iota, t) H_{6_i}(\iota) \hat{C}_j(\iota) \end{array} \right]^T \times \\
&\quad \left[\begin{array}{c} C_{1_m}(\iota) + F(x(t), \iota, t) H_{4_m}(\iota) \quad D_{12_m}(\iota) \hat{C}_n(\iota) + F(x(t), \iota, t) H_{6_m}(\iota) \hat{C}_n(\iota) \end{array} \right] \tilde{x}(t) \\
&\leq \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \left(2\aleph^2(\iota) \tilde{x}^T(t) \left[\begin{array}{c} C_{1_i}(\iota) \quad D_{12_i}(\iota) \hat{C}_j(\iota) \end{array} \right]^T \times \right. \\
&\quad \left. \left[\begin{array}{c} C_{1_m}(\iota) \quad D_{12_m}(\iota) \hat{C}_n(\iota) \end{array} \right] \tilde{x}(t) + 2\aleph^2(\iota) \rho^2(\iota) \tilde{x}^T(t) \times \right. \\
&\quad \left. \left[\begin{array}{c} H_{4_i}(\iota) \quad H_{6_i}(\iota) \hat{C}_j(\iota) \end{array} \right]^T \left[\begin{array}{c} H_{4_m}(\iota) \quad H_{6_m}(\iota) \hat{C}_n(\iota) \end{array} \right] \tilde{x}(t) \right) \quad (\text{A.58})
\end{aligned}$$

where $\aleph(\iota) \geq \left(1 + \rho^2(\iota) \left[\|H_{2_i}^T(\iota) H_{2_j}(\iota)\| + \|H_{7_i}^T(\iota) H_{7_j}(\iota)\| \right] \right)^{\frac{1}{2}}$. Hence,

$$\begin{aligned}
 & \gamma^2 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n [\tilde{w}^T(t) \tilde{w}(t)] + \aleph^2(\iota) z^T(t) z(t) \\
 & \leq \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \left(\tilde{x}^T(t) \left[\tilde{C}_{1_i}(\iota) \quad \tilde{D}_{12_i}(\iota) \hat{C}_j(\iota) \right]^T \times \right. \\
 & \quad \left. \left[\tilde{C}_{1_m}(\iota) \quad \tilde{D}_{12_m}(\iota) \hat{C}_n(\iota) \right] \tilde{x}(t) \right) + \aleph^2(\iota) \gamma^2 w^T(t) w(t) \tag{A.59}
 \end{aligned}$$

where

$$\begin{aligned}
 \tilde{C}_{1_i}(\iota) &= \left[\frac{\gamma \rho(\iota)}{\delta(\iota)} H_{1_i}^T(\iota) \quad 0 \quad \frac{\gamma \rho(\iota)}{\delta(\iota)} H_{5_i}^T(\iota) \quad \sqrt{2} \aleph(\iota) \rho(\iota) H_{4_i}^T(\iota) \quad \sqrt{2} \aleph(\iota) C_{1_i}^T(\iota) \right]^T \\
 \tilde{D}_{12_i}(\iota) &= \left[0 \quad \frac{\gamma \rho(\iota)}{\delta(\iota)} H_{3_i}^T(\iota) \quad 0 \quad \sqrt{2} \aleph(\iota) \rho(\iota) H_{6_i}^T(\iota) \quad \sqrt{2} \aleph(\iota) D_{12_i}^T(\iota) \right]^T.
 \end{aligned}$$

Substituting (A.59) into (A.56), we have

$$\begin{aligned}
 \tilde{\Delta}V(x(t), \iota) &\leq -\aleph^2(\iota) z^T(t) z(t) + \gamma^2 \aleph^2(\iota) w^T(t) w(t) \\
 &\quad + \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \Omega_{ijmn}(\iota) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \tag{A.60}
 \end{aligned}$$

where

$$\Omega_{ijmn}(\iota) = \begin{pmatrix} \begin{pmatrix} (A_{cl}^{ij}(\iota))^T P(\iota) + P(\iota) A_{cl}^{ij}(\iota) \\ +(C_{cl}^{ij}(\iota))^T C_{cl}^{mn}(\iota) + \sum_{k=1}^s \lambda_{ik} P(k) \\ (B_{cl}^{ij}(\iota))^T P(\iota) \end{pmatrix} & \begin{pmatrix} (*)^T \\ -\gamma^2 I \end{pmatrix} \end{pmatrix}. \tag{A.61}$$

Using the fact

$$\begin{aligned}
 \sum_{i=1}^r \sum_{j=1}^r \sum_{m=1}^r \sum_{n=1}^r \mu_i \mu_j \mu_m \mu_n M_{ij}^T(\iota) N_{mn}(\iota) &\leq \frac{1}{2} \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j [M_{ij}^T(\iota) M_{ij}(\iota) \\
 &\quad + N_{ij}(\iota) N_{ij}^T(\iota)],
 \end{aligned}$$

we can rewrite (A.61) as follows:

$$\begin{aligned}
 \tilde{\Delta}V(x(t), \iota) &\leq -\aleph^2(\iota) z^T(t) z(t) + \gamma^2 \aleph^2(\iota) w^T(t) w(t) \\
 &\quad + \sum_{i=1}^r \sum_{j=1}^r \mu_i \mu_j \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix}^T \Omega_{ij}(\iota) \begin{bmatrix} x(t) \\ \tilde{w}(t) \end{bmatrix} \tag{A.62}
 \end{aligned}$$

where

$$\Omega_{ij}(\iota) = \begin{pmatrix} \begin{pmatrix} (A_{cl}^{ij}(\iota))^T P(\iota) + P(\iota) A_{cl}^{ij}(\iota) \\ +(C_{cl}^{ij}(\iota))^T C_{cl}^{ij}(\iota) + \sum_{k=1}^s \lambda_{ik} P(k) \\ (B_{cl}^{ij}(\iota))^T P(\iota) \end{pmatrix} & \begin{pmatrix} (*)^T \\ -\gamma^2 I \end{pmatrix} \end{pmatrix}. \tag{A.63}$$

Note that (A.63) is the Schur complement of (5.26). Using the inequality (5.26), we have

$$\tilde{\Delta}V(x(t), \iota) < -\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t). \quad (\text{A.64})$$

Applying the operator $\mathbf{E}[\int_0^{T_f}(\cdot)dt]$ on both sides of (A.64), we obtain

$$\mathbf{E} \left[\int_0^{T_f} \tilde{\Delta}V(x(t), \iota) dt \right] < \mathbf{E} \left[\int_0^{T_f} (-\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t)) dt \right]. \quad (\text{A.65})$$

From the Dynkin's formula [75], it follows that

$$\mathbf{E} \left[\int_0^{T_f} \tilde{\Delta}V(x(t), \iota) dt \right] = \mathbf{E}[V(x(T_f), \iota(T_f))] - \mathbf{E}[V(x(0), \iota(0))]. \quad (\text{A.66})$$

Substitute (A.66) into (A.65) yields

$$0 < \mathbf{E} \left[\int_0^{T_f} (-\aleph^2(\iota)z^T(t)z(t) + \gamma^2\aleph^2(\iota)w^T(t)w(t)) dt \right] - \mathbf{E}[V(x(T_f), \iota(T_f))] + \mathbf{E}[V(x(0), \iota(0))].$$

Using (A.49) and the fact that $V(x(0), \iota(0)) = 0$ and $V(x(T_f), \iota(T_f)) > 0$, we have

$$\mathbf{E} \left[\int_0^{T_f} \left\{ z^T(t)z(t) - \gamma^2 w^T(t)w(t) \right\} dt \right] < 0. \quad (\text{A.67})$$

Hence the inequality (5.5) holds. This completes the proof of Lemma 3. \blacksquare

Proof of Theorem 8.2

Suppose the inequalities (8.36)-(8.38) hold, then the matrices X_0 and Y_0 are of the following forms:

$$X_0 = \begin{pmatrix} X_1 & X_2 \\ 0 & X_3 \end{pmatrix} \quad \text{and} \quad Y_0 = \begin{pmatrix} Y_1 & Y_2 \\ 0 & Y_3 \end{pmatrix}$$

with $X_1 = X_1^T > 0$, $X_3 = X_3^T > 0$, $Y_1 = Y_1^T > 0$ and $Y_3 = Y_3^T > 0$. Substituting X_0 and Y_0 into (8.47), respectively, we have

$$X_\varepsilon = \left\{ X_0 + \varepsilon \tilde{X} \right\} E_\varepsilon = \begin{pmatrix} X_1 & \varepsilon X_2 \\ \varepsilon X_2^T & \varepsilon X_3 \end{pmatrix}. \quad (\text{A.68})$$

and

$$Y_\varepsilon^{-1} = \left\{ Y_0^{-1} + \varepsilon N_\varepsilon \right\} E_\varepsilon = \begin{pmatrix} Y_1^{-1} & -\varepsilon Y^{-1} Y_2 Y_3^{-1} \\ -\varepsilon (Y^{-1} Y_2 Y_3^{-1})^T & \varepsilon Y_3^{-1} \end{pmatrix}. \quad (\text{A.69})$$

Clearly, $X_\varepsilon = X_\varepsilon^T$, and $Y_\varepsilon^{-1} = (Y_\varepsilon^{-1})^T$. Knowing the fact that the inverse of a symmetric matrix is a symmetric matrix, we learn that Y_ε is a symmetric matrix. Using the matrix inversion lemma, we can see that

$$Y_\varepsilon = E_\varepsilon^{-1} \left\{ Y_0 + \varepsilon \tilde{Y} \right\} \tag{A.70}$$

where $\tilde{Y} = Y_0 N_\varepsilon (I + \varepsilon Y_0 N_\varepsilon)^{-1} Y_0$. Employing the Schur complement, one can show that there exists a sufficiently small $\hat{\varepsilon}$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (8.26) and (8.27) hold.

Now, we need to show that

$$\begin{pmatrix} X_\varepsilon & I \\ I & Y_\varepsilon \end{pmatrix} > 0. \tag{A.71}$$

By the Schur complement, it is equivalent to showing that

$$X_\varepsilon - Y_\varepsilon^{-1} > 0. \tag{A.72}$$

Substituting (A.68) and (A.69) into the left hand side of (A.72), we get

$$\begin{bmatrix} X_1 - Y_1^{-1} & \varepsilon(X_2 + Y_1^{-1}Y_2Y_3^{-1}) \\ \varepsilon(X_2 + Y_1^{-1}Y_2Y_3^{-1})^T & \varepsilon(X_3 - Y_3^{-1}) \end{bmatrix}. \tag{A.73}$$

The Schur complement of (8.36) is

$$\begin{bmatrix} X_1 - Y_1^{-1} & 0 \\ 0 & X_3 - Y_3^{-1} \end{bmatrix} > 0. \tag{A.74}$$

According to (A.74), we learn that

$$X_1 - Y_1^{-1} > 0 \quad \text{and} \quad X_3 - Y_3^{-1} > 0. \tag{A.75}$$

Using (A.75) and the Schur complement, it can be shown that there exists a sufficiently small $\hat{\varepsilon} > 0$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (8.25) holds.

Next, employing (A.68), (A.69) and (A.70), the controller's matrices given in (8.34) can be re-expressed as follows:

$$\begin{aligned} \mathcal{B}_i(\varepsilon) &= [Y_0^{-1} - X_0] \hat{B}_i + \varepsilon [N_\varepsilon - \tilde{X}] \hat{B}_i \triangleq \mathcal{B}_{0_i} + \varepsilon \mathcal{B}_{\varepsilon_i} \\ \mathcal{C}_i(\varepsilon) &= \hat{C}_i Y_0^T + \varepsilon \hat{C}_i \tilde{Y}^T \triangleq \mathcal{C}_{0_i} + \varepsilon \mathcal{C}_{\varepsilon_i}. \end{aligned} \tag{A.76}$$

Substituting (A.68), (A.69), (A.70) and (A.76) into (8.32) and (8.33), and pre-post multiplying (8.32) by $\begin{pmatrix} E_\varepsilon & 0 \\ 0 & I \end{pmatrix}$, we, respectively, obtain

$$\Psi_{11_{ij}} + \psi_{11_{ij}} \quad \text{and} \quad \Psi_{22_{ij}} + \psi_{22_{ij}} \tag{A.77}$$

where the ε -independent linear matrices $\Psi_{11_{ij}}$ and $\Psi_{22_{ij}}$ are defined in (8.43) and (8.44), respectively and the ε -dependent linear matrices are

$$\psi_{11_{ij}} = \varepsilon \begin{pmatrix} A_i \tilde{Y}^T + \tilde{Y} A_i^T + B_{2_i} C_{\varepsilon_j} + C_{\varepsilon_i}^T B_{2_j}^T (*)^T & \\ \left[\tilde{Y} \tilde{C}_{1_i}^T + C_{\varepsilon_i}^T \tilde{D}_{1_{2_j}}^T \right]^T & 0 \end{pmatrix} \quad (\text{A.78})$$

$$\psi_{22_{ij}} = \varepsilon \begin{pmatrix} A_i^T \tilde{X} + \tilde{X}^T A_i + B_{\varepsilon_i} C_{2_j} + C_{2_i}^T B_{\varepsilon_j}^T (*)^T & \\ \left[\tilde{X} \tilde{B}_{1_i} + B_{\varepsilon_i} \tilde{D}_{2_{1_j}} \right]^T & 0 \end{pmatrix}. \quad (\text{A.79})$$

Note that the ε -dependent linear matrices tend to zero when ε approaches zero.

Employing (8.39)–(8.42) and knowing the fact that for any given negative definite matrix \mathcal{W} , there exists an $\varepsilon > 0$ such that $\mathcal{W} + \varepsilon I < 0$, one can show that there exists a sufficiently small $\hat{\varepsilon} > 0$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (8.28)–(8.31) hold. Since (8.25)–(8.31) hold, using Lemma 8.2, the inequality (3.3) holds. ■

Proof of Theorem 10.2

Suppose the inequalities (10.56)–(10.58) hold, then the matrices $X_0(\iota)$ and $Y_0(\iota)$ are of the following forms:

$$X_0(\iota) = \begin{pmatrix} X_1(\iota) & X_2(\iota) \\ 0 & X_3(\iota) \end{pmatrix} \quad \text{and} \quad Y_0(\iota) = \begin{pmatrix} Y_1(\iota) & Y_2(\iota) \\ 0 & Y_3(\iota) \end{pmatrix}$$

with $X_1(\iota) = X_1^T(\iota) > 0$, $X_3(\iota) = X_3^T(\iota) > 0$, $Y_1(\iota) = Y_1^T(\iota) > 0$ and $Y_3(\iota) = Y_3^T(\iota) > 0$. Substituting $X_0(\iota)$ and $Y_0(\iota)$ into (10.67)–(10.68), respectively, we have

$$X_\varepsilon(\iota) = \begin{pmatrix} X_1(\iota) & \varepsilon X_2(\iota) \\ \varepsilon X_2^T(\iota) & \varepsilon X_3(\iota) \end{pmatrix} \quad (\text{A.80})$$

and

$$Y_\varepsilon^{-1}(\iota) = \begin{pmatrix} Y_1^{-1}(\iota) & -\varepsilon Y^{-1}(\iota) Y_2(\iota) Y_3^{-1}(\iota) \\ -\varepsilon \left(Y^{-1}(\iota) Y_2(\iota) Y_3^{-1}(\iota) \right)^T & \varepsilon Y_3^{-1}(\iota) \end{pmatrix}. \quad (\text{A.81})$$

Clearly, $X_\varepsilon(\iota) = X_\varepsilon^T(\iota)$, and $Y_\varepsilon^{-1}(\iota) = (Y_\varepsilon^{-1}(\iota))^T$. Knowing the fact that the inverse of a symmetric matrix is a symmetric matrix, we learn that $Y_\varepsilon(\iota)$ is a symmetric matrix. Using the matrix inversion lemma, we can see that $Y_\varepsilon(\iota) = E_\varepsilon^{-1} \left\{ Y_0(\iota) + \varepsilon \tilde{Y}(\iota) \right\}$ where $\tilde{Y}(\iota) = Y_0(\iota) N_\varepsilon(\iota) (I + \varepsilon Y_0(\iota) N_\varepsilon(\iota))^{-1} Y_0(\iota)$. Employing the Schur complement, one can show that there exists a sufficiently small $\hat{\varepsilon}$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (10.46) and (10.47) hold.

Now, we need to show that

$$\begin{pmatrix} X_\varepsilon(\iota) & I \\ I & Y_\varepsilon(\iota) \end{pmatrix} > 0. \quad (\text{A.82})$$

By the Schur complement, it is equivalent to showing that

$$X_\varepsilon(\iota) - Y_\varepsilon^{-1}(\iota) > 0. \quad (\text{A.83})$$

Substituting (A.80) and (A.81) into the left hand side of (A.83), we get

$$\begin{bmatrix} X_1(\iota) - Y_1^{-1}(\iota) & \varepsilon(X_2(\iota) + Y_1^{-1}(\iota)Y_2(\iota)Y_3^{-1}(\iota)) \\ \varepsilon(X_2(\iota) + Y_1^{-1}(\iota)Y_2(\iota)Y_3^{-1}(\iota))^T & \varepsilon(X_3(\iota) - Y_3^{-1}(\iota)) \end{bmatrix}. \quad (\text{A.84})$$

The Schur complement of (10.56) is

$$\begin{bmatrix} X_1(\iota) - Y_1^{-1}(\iota) & 0 \\ 0 & X_3(\iota) - Y_3^{-1}(\iota) \end{bmatrix} > 0. \quad (\text{A.85})$$

According to (A.85), we learn that

$$X_1(\iota) - Y_1^{-1}(\iota) > 0 \quad \text{and} \quad X_3(\iota) - Y_3^{-1}(\iota) > 0. \quad (\text{A.86})$$

Using (A.86) and the Schur complement, it can be shown that there exists a sufficiently small $\hat{\varepsilon} > 0$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (10.45) holds.

Next, employing (A.80) and (A.81), the controller's matrices given in (10.54) can be re-expressed as follows:

$$\begin{aligned} \mathcal{B}_i(\iota, \varepsilon) &= [Y_0^{-1}(\iota) - X_0(\iota)]\hat{B}_i(\iota) + \varepsilon[N_\varepsilon(\iota) - \tilde{X}(\iota)]\hat{B}_i(\iota) \triangleq \mathcal{B}_{0_i}(\iota) + \varepsilon\mathcal{B}_{\varepsilon_i}(\iota) \\ \mathcal{C}_i(\iota, \varepsilon) &= \hat{C}_i(\iota)Y_0^T(\iota) + \varepsilon\hat{C}_i(\iota)\tilde{Y}^T(\iota) \triangleq \mathcal{C}_{0_i}(\iota) + \varepsilon\mathcal{C}_{\varepsilon_i}(\iota). \end{aligned} \quad (\text{A.87})$$

Substituting (A.80),(A.81) and (A.87) into (10.52) and (10.53), and pre-post multiplying (10.52) by $\begin{pmatrix} E_\varepsilon & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & I \end{pmatrix}$, we respectively, obtain

$$\Psi_{11_{ij}}(\iota) + \psi_{11_{ij}}(\iota) \quad \text{and} \quad \Psi_{22_{ij}}(\iota) + \psi_{22_{ij}}(\iota) \quad (\text{A.88})$$

where the ε -independent linear matrices $\Psi_{11_{ij}}(\iota)$ and $\Psi_{22_{ij}}(\iota)$ are defined in (10.63) and (10.64), respectively, and the ε -dependent linear matrices are

$$\psi_{11_{ij}}(\iota) = \varepsilon \begin{pmatrix} \begin{pmatrix} A_i(\iota)\tilde{Y}^T(\iota) + \tilde{Y}(\iota)A_i^T(\iota) \\ +B_{2_i}(\iota)\mathcal{C}_{\varepsilon_j}(\iota) + \mathcal{C}_{\varepsilon_i}^T(\iota)B_{2_j}^T(\iota) \\ +\lambda_{ii}\hat{\tilde{X}}(\iota) \end{pmatrix} (*)^T \quad (*)^T \\ \tilde{C}_{1_i}(\iota)\tilde{Y}^T(\iota) + \tilde{D}_{12_i}(\iota)\mathcal{C}_{\varepsilon_j}(\iota) \quad 0 \quad (*)^T \\ \tilde{\mathcal{J}}^T(\iota) \quad 0 \quad -\tilde{Y}(\iota) \end{pmatrix} \quad (\text{A.89})$$

and

$$\psi_{22_{ij}}(\iota) = \varepsilon \begin{pmatrix} \begin{pmatrix} A_i^T(\iota)\tilde{X}^T(\iota) + \tilde{X}(\iota)A_i(\iota) \\ +\mathcal{B}_{\varepsilon_i}(\iota)\mathcal{C}_{2_j}(\iota) + \mathcal{C}_{2_i}^T(\iota)\mathcal{B}_{\varepsilon_j}^T(\iota) \\ +\sum_{k=1}^s \lambda_{ik}\hat{\tilde{X}}(k) \end{pmatrix} (*)^T \\ \tilde{B}_{1_i}^T(\iota)\tilde{X}^T(\iota) + \tilde{D}_{21_i}^T(\iota)\mathcal{B}_{\varepsilon_j}^T(\iota) \quad 0 \end{pmatrix} \quad (\text{A.90})$$

where $\tilde{\mathcal{J}}(\iota) = \left[\sqrt{\lambda_{1\iota}} \hat{Y}(\iota) \quad \cdots \quad \sqrt{\lambda_{(i-1)\iota}} \hat{Y}(\iota) \quad \sqrt{\lambda_{(i+1)\iota}} \hat{Y}(\iota) \quad \cdots \quad \sqrt{\lambda_{s\iota}} \hat{Y}(\iota) \right]$,
 $\tilde{\mathcal{Y}}(\iota) = \text{diag} \left\{ \hat{Y}(1), \quad \cdots, \quad \hat{Y}(\iota - 1), \quad \hat{Y}(\iota + 1), \quad \cdots, \quad \hat{Y}(s) \right\}$, $\hat{X}(k) = \frac{\tilde{X}(k) + \tilde{X}^T(k)}{2}$ and $\hat{Y}(\iota) = \frac{\tilde{Y}(\iota) + \tilde{Y}^T(\iota)}{2}$. Note that the ε -dependent linear matrices tend to zero when ε approaches zero.

Employing (10.59)-(10.62) and knowing the fact that for any given negative definite matrix \mathcal{W} , there exists an $\varepsilon > 0$ such that $\mathcal{W} + \varepsilon I < 0$, one can show that there exists a sufficiently small $\hat{\varepsilon} > 0$ such that for $\varepsilon \in (0, \hat{\varepsilon}]$, (10.48)-(10.51) hold. Since (10.45)-(10.51) hold, using Lemma 9, the inequality (5.5) holds. ■

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